



Manless operation of aerial ropeways

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Operation of aerial ropeways without present staff



- → Definition / introduction / examples
- → Regulations
- → How to ensure the same safety level as with an operator in every station?
- → Feedback from STRMTG on such systems



Operation of aerial ropeways without present staff



- → On « usual » installations, one or more operators in every ropeway station, and in certain cases in big vehicles
- → On the more rare installations without present staff, it doesn't mean that the operation is totally manless, but there isn't an operator in every station
- → Main question: keeping the same safety level as with the operator, on the various aspects of her/his monitoring/management missions:
 - → Safety of passagers in the stations :
 - → In link with the installation,
 - → Interface with cabins, loading/unloading,
 - → Embarked weight,
 - → Weather conditions,
 - → Alarms and automatic stops, and resetting them,
 - → Evacuation,
 - → Fire risk.



Examples of aerial ropeways in France without present staff



- → Jigback operation :
 - → Funitel « Trois Vallées (Bouquetin) » in Val Thorens POMA 2003
 - → Gondola « Télébuffette » in Montchavin Leitner 2008
 - → Funitel « Thorens » in Val Thorens BMF 2011
 - → Gondola « Petit Moriond » in Courchevel POMA 2012
 - → Jigback cable car « Dahu » in les Arcs BMF 2015
 - → Jigback cable car in Brest BMF 2016
 - → Jigback cable car project in Orléans POMA 2018
- → Continuous movement operation :
 - → Gondola « Cairn-Caron » in Val Thorens Doppelmayr 2007
 - → Gondola project « Moraine » in Val Thorens Doppelmayr 2017
- → Installations used as examples throughout the rest of the presentation



Where is the operator?



- → Only one operator in a station for several stations on the installation
- → (Cairn-Caron, Trois Vallées)
- → Operator positionned and already supervising another installation
- → (Thorens, Moraine project)
- → Operator in a remote control room
- → (Dahu, Brest, Orléans project)
- → Choice sometimes possible between these options
- → (Télébuffette, Petit Moriond)



→ FT Thorens : photo taken from chairlift Portette top station, operator position



Regulations



- → No special mention or treatment in the EN standards
- → In french texts, a few recent evolutions in RM1 regulation guide :
 - → Possibility to operate with cabins >40people without staff on board, but with bidirectionnal communication equipments with an operator
 - → Not referring to the installation driver anymore, but to the driving missions, in link with the Safety Management Systems
 - → But otherwise, no particular explicit specifications on systems without present staff
- → French control authorities (STRMTG) ask for a special risk analysis for operation without staff, with the following main attention points...



Passenger safety in stations in link with the aerial ropeway



- → Turning parts must be unreachable
- → (Prevention of abnormal behaviours, especially for urban uses)





TPH Brest, Jean Moulin station

Passenger / cabin interface for jigback operation



Risks : passenger falling from the platform, going under a cabin, stuck in the doors congress 2017 while cabin departing

- → Most obvious solution : Platform Screen Doors (PSDs)
- → Or combination of:
 - → Immaterial barriers detecting falls (not too high) from the platform
 - → Detection of bad loadings

→ In both cases, alarm / stopping buttons accessible to users on the platforms, discussion

on what they do depending on cabin position







→ FT Trois Vallées – Bouquetin : bottom pit and platform detection cells

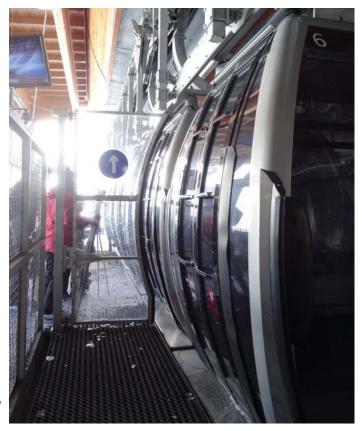
Passenger/cabin interface for continuous movement operation

- OITAF

 Bozen/Bolzano
 Congress 2017
- → Gondola Cairn-Caron, managed by a « moving cabin wall » in the station :
 - Special parts on the side of the cabins avoiding gaps between cabins
 - Chain with fingers in the upper part ensuring vehicle spacement
 - Sensitive area at the end of the platform to stop in case of bad loading/unloading
- → New systems in development for new projects



 TC Cairn-Caron, top of Cairn station



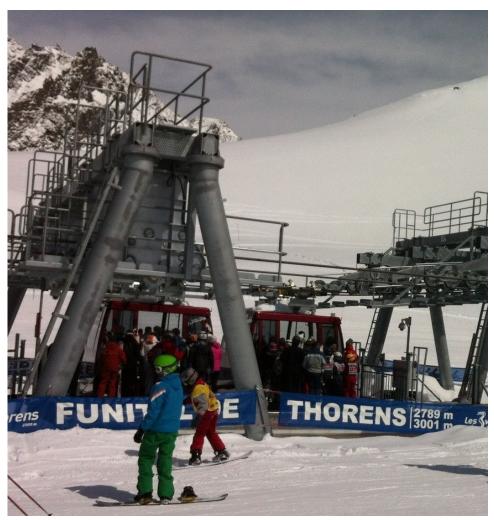
Bozen/Bolzano 6 - 9 June 2017



Embarked weight management



- → Needed to ensure absence of overweight / conditions of use of the cabins
- → As nobody can estimate the number of embarked passengers on-site or control people going over counting barriers for jigbacks, need for :
 - → physical limitation inside the cabins,
 - → and/or an integrated control system preventing departure in case of overweight (often already used to calculate cabin with 3500N/m²)





Management of weather conditions



- → Compared to an usual installation, as the operator may not « feel » the conditions in every station :
 - → Increased importance of wind sensors, possibly with intermediate alarms before stopping the installation,
 - → Increased importance of checking weather forecast / reports daily before operation to know likely conditions to expect,
 - → Increased importance of the daily morning visit before operation (for ex if it snowed the night before),
 - → Video cameras in stations and possibly on the line to see what happens



→ FT Bouquetin



Management of alarms / automatic stops



- → A few of them are resettable remotely, but the most critical are not!
- → Necessity of operator on-site for many alarms / stops, and necessity of a limited / well-defined delay for the operator to come
- → Examples of usual discussions on alarms on such systems :
 - → Resettable remotely after a passenger alarm button on the platform (classical subject on automatic underground railway systems) ?...
 - → ...and should the system stop or not depending on the cabin position ?
 - → Automatic stop due to a short gust of wind : when to reset, from where, and relaunch with which speed ?



Evacuation



- → With PSDs, question of passenger auto-evacuation when the cabin is stopped close enough from the station
- → It should be possible to unlock the door from inside the cabin, and not dangerous to get out



 TPH Brest, Capucins and Jean Moulin stations





Fire risk management



- → Need for a specific risk analysis for each installation (real risk under the line / in the stations, cycle time, ...)
- → Early detection of the fire can't be done by the operator, especially in/near stations...
- → ...hence importance of the communication system with the passengers, particularly in case of operator in a remote control center and/or in cities
- → Questions raised in link with « fire emergency mode » without staff in the station :
 - → In case of fire, should it be triggered straight away, or would ending the current cycle and blocking next departure be enough first?
 - → Where are the triggers for the « fire emergency mode » ?
 - → On-site → more time to reach them,
 - → Remote → complicated to secure the link, including fire-proof it



STRMTG feedback on aerial ropeway operation without present staff



- → No serious incident so far, but few such installations in service
- → Few occurrences of an operator having to access on-site to solve a problem
- → The safety analysis demonstrates that safety level is at least as good as an installation with present staff
- → (Cost efficiency: more complicated systems, so more expensive to conceive / build)
- → A ropeway without present staff is a complex system, it should not be handled as an elevator or an escalator!
- → Usual staffed ropeway reflexes must be kept, in particular to reset alarms / automats and manage weather conditions
- → The operation without staff should remain an operation mode the operator can give up at any moment





